## CONDITIONS FOR FINITE SIGNAL SPEED IN RELAXATIONAL INFILTRATION

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Relaxation effects can occur in the interaction between the rock skeleton and the fluid during nonstationary liquid or gas infiltration [1-3]. The frequency dependence of the permeability has been considered repeatedly in the literature since the appearance of [4, 5]. In [6], the finite signal propagation rate was examined for a linearly elastic porous medium saturated with a compressible fluid. However, a fairly serious assumption was made [6] on the boundedness of the relaxation kernel at short times, even though it was stated that there are examples where this condition is not met.

Here I examine the finite signal speed for the case where the relaxation kernel may have singularities at short times.

I consider a homogeneous isotropic linearly-elastic porous medium saturated with a compressible fluid. I describe the possible dynamic processes by means of the [6, 7] symbols:  $\rho_1$  the solid-phase density,  $\rho_2$  the liquid-phase density, m porosity,  $l_i$  the solid-phase displacement vector,  $w_i$  the mean particle velocity in the liquid phase,  $\sigma_{ij}$  the solid-phase stress tensor, and p the pressure in the liquid phase. The Latin subscripts run through the range 1, 2, and 3, which correspond to the coordinates in the Ox<sup>1</sup>x<sup>2</sup>x<sup>3</sup> Cartesian system, with summation with respect to the related subscripts; t is time. All the processes are assumed to be isothermal.

In the linearly elastic formulation,

$$\sigma_{ij} = \lambda_1 e \delta_{ij} + 2\lambda_2 e_{ij}, \quad e_{ij} = \frac{1}{2} \left( \frac{\partial l_i}{\partial x^i} + \frac{\partial l_j}{\partial x^i} \right), \quad e = e_{ij}, \tag{1}$$

in which  $\lambda_{\alpha}$  are the Lamé coefficients. Let  $R_i$  be the interaction between the liquid and solid phases. We use an expression from relaxation theory for it [6]:

$$R_i\Big|_{t_0} = \frac{\mu m^2}{k} \int_{-\infty}^{t_0} K\left(t_0 - t\right) \left(w_i - \frac{\partial l_i}{\partial t}\right)\Big|_t dt.$$
<sup>(2)</sup>

Here  $\mu$  is the shear viscosity, k the permeability, and K(t) the relaxation kernel, which is normalized in such a way that

$$\int_{0}^{+\infty} K(t) dt = 1.$$
 (3)

Consider the propagation of weak perturbations in this two-phase medium. Subscript 0 is used with quantities relating to the unperturbed state. Let  $\rho_{\alpha}' = \rho_{\alpha} - \rho_{\alpha 0}$  ( $\alpha = 1, 2$ ) be the perturbations in the density patterns. We use linear expressions for the pressure and porosity:  $p = p_0 + c^2 \rho_2'$ ,  $m = m_0 + a_2 \rho_2' - a_1 \rho_1'$ , with c the isothermal speed of sound.

The following are the dynamic equations for the perturbations derived from (1) and (2) in the absence of sources:

$$\frac{\partial}{\partial t} \left( \alpha_1 \rho_1' - \alpha_2 \rho_2' \right) + \frac{\partial^2 l_i}{\partial t \, \partial x^i} = 0, \quad \frac{\partial}{\partial t} \left( -\beta_1 \rho_1' + \beta_2 \rho_2' \right) + \frac{\partial w_i}{\partial x^i} = 0, \tag{4}$$

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$$\frac{\partial}{\partial x^{i}} \left( -\zeta_{1} \rho_{1}^{\prime} + \zeta_{2} \rho_{2}^{\prime} \right) + \left( \frac{\partial^{2} l_{i}}{\partial t^{2}} - \eta_{1} \frac{\partial^{2} l_{j}}{\partial x^{i} \partial x^{j}} - \eta_{2} \Delta l_{i} - \nu K * \frac{\partial l_{i}}{\partial t} \right) - \nu K * w_{i} = 0$$

$$\gamma \frac{\partial \rho_{2}^{\prime}}{\partial x^{i}} - \delta K * \frac{\partial l_{i}}{\partial t} + \delta K * w_{i} + \frac{\partial w_{i}}{\partial t} = 0.$$

When there are sources, the corresponding terms must be inserted on the right in (4). The following symbols [6] are used in (4): \* time convolution,

$$\begin{aligned} \alpha_1 &= \rho_{10}^{-1} + a_1 \left( 1 - m_0 \right)^{-1}; \quad \alpha_2 &= a_2 \left( 1 - m_0 \right)^{-1}; \\ \beta_1 &= a_1 m_0^{-1}; \quad \beta_2 &= \rho_{20}^{-1} + a_2 m_0^{-1}; \quad \eta_1 &= \left( \lambda_{10} + \lambda_{20} \right) \rho_{10}^{-1}; \quad \eta_2 &= \lambda_{20} \rho_{10}^{-1}; \\ \zeta_1 &= p_0 a_1 \left( 1 - m_0 \right)^{-1} \rho_{10}^{-1}; \quad \zeta_2 &= p_0 a_2 \left( 1 - m_0 \right)^{-1} \rho_{20}^{-1}; \\ \nu &= m_0^2 \mu_0 \left( 1 - m_0 \right)^{-1} k_0^{-1} \rho_{10}^{-1}; \quad \gamma &= c^2 \rho_{20}^{-1}; \quad \delta &= m_0 \mu_0 k_0^{-1} \rho_{20}^{-1}. \end{aligned}$$

We recall the properties of the Fourier transform for the kernel  $\tilde{K} = \tilde{K}(\omega)$  [6] ( $\tilde{K} = \tilde{K}(\omega)$  is a complex function holomorphic in the lower complex plane). In accordance with (3),  $\tilde{K}(0) = 1$ . For real  $\omega$ , we have the thermodynamic inequality

$$\operatorname{Re} \tilde{K}(\omega) > 0. \tag{5}$$

Consider the behavior of  $\tilde{K}(\omega)$  for  $|\omega| \rightarrow +\infty$ , Im  $\omega \leq 0$ . The asymptote adopted in [6] was

$$\tilde{K}(\omega) = K(0) (i\omega)^{-1} + O(|\omega|^{-1}),$$
(6)

and corresponds to the case where K(t) is a smooth function for  $t \ge 0$ . We now consider the wider class of asymptotes

$$K(\omega) = \chi (i\omega)^{\epsilon} + O(|\omega|^{\epsilon}).$$
<sup>(7)</sup>

Here x and  $\varepsilon$  are real numbers and x > 0;  $-1 \le \varepsilon \le 1$ . The (7) asymptote class is compatible with (5) and includes (6) as a particular case. It also covers standard exact solutions for the resistance forces acting on a body moving in a linearly-viscous liquid at a variable speed [6]. As the asymptote to  $\tilde{K}(\omega)$  at high frequencies is determined by the asymptote to K(t) at short times, (7) means that the convolution operation with relaxational kernel can be written as

$$K * = \varkappa_{-\infty} D^{t} + z,$$

where the first term is the fractional time derivative [8] and z is a pseudodifferential operator of higher-order smoothness.

It follows from (5) and (7) that (5) is obeyed throughout the lower complex half-plane.

I now consider perturbations propagating from a certain source of mass or force that acts at time t = 0 at the origin. We concentrate attention on perturbations at a point in space  $x_0^j = L\delta_1^j$ , L > 0. We use the [6] method to get an expression for the Fourier transforms of the perturbations in the density, velocity, and displacement patterns:

$$y(\omega) = 2\pi i \sum_{\alpha=1}^{3} \operatorname{Res}_{n_{\alpha}(\omega)} \left[ \frac{e^{inL} N(\omega, n) q}{P_{1}^{2}(\omega, n) P_{2}(\omega, n)} \right].$$
(8)

Here  $n_{\alpha} = n_{\alpha}(\omega)$ ;  $\alpha = 1, 2, 3$  are the roots of the equations

$$P_1 = 0; (9)$$

$$P_2 = 0,$$
 (10)

that satisfy Im  $n_{\alpha} > 0$ ; while  $P_1$  and  $P_2$  are polynomials in the complex variable n:

$$P_1 = (-\omega + i\delta\tilde{K}) n^2 + \eta_2^{-1}\omega^2 (\omega - i(\nu + \delta)\tilde{K}),$$
  

$$P_2 = An^4 + (-\omega^2 B + i\omega C\tilde{K}) n^2 + i\omega^4 - i\omega^3 D\tilde{K},$$

$$A = C_1 C_4 - C_2 C_3, \quad B = C_1 + C_2, \quad C = \nu \ (C_1 + C_4) + \delta \ (C_2 + C_3), \quad D = \nu + \delta_3,$$

$$C_1 = \eta_1 + \eta_2 + (\beta_1 \zeta_2 - \beta_2 \zeta_1) / (\alpha_1 \beta_2 - \alpha_2 \beta_1),$$

$$C_2 = (\alpha_1 \zeta_2 - \alpha_2 \zeta_1) / (\alpha_1 \beta_2 - \alpha_2 \beta_1),$$

$$C_3 = \gamma \beta_1 / (\alpha_1 \beta_2 - \alpha_2 \beta_1), \quad C_4 = \gamma \alpha_1 / (\alpha_1 \beta_2 - \alpha_2 \beta_1).$$

In (8), N( $\omega$ , n) is a matrix homomorphically dependent on  $\omega$  for Im  $\omega < 0$  and polynomially dependent on n, while q is a constant vector.

The central point in calculating the perturbation propagation speed is the proof that  $n_{\alpha}(\omega)$  never intersects the real axis when  $\omega$  varies in the lower complex half-plane, i.e., it holomorphically maps the lower complex half-plane into the upper one. If this is proved, one gets the velocities  $V_{\alpha}$  for the various modes of perturbation from [6]

$$V_{\alpha} = \left(\lim_{\substack{|\omega| \to +\infty\\ I_{m}\,\omega < 0}} (\operatorname{Im} n_{\alpha} \,(\omega)/(-\operatorname{Im} \,\omega))\right),\tag{11}$$

which is a standard result for problems of that type [9, 10]. We thus show that (9) and (10) as functions of n do not have real solutions for Im  $\omega < 0$ . It is readily seen that for this purpose it is sufficient to show that the functions of parameter  $\omega$  for real n are

$$X_{1}(\omega) = \tilde{K} + i\omega (\omega^{2} - \eta_{2}n^{2}) ((\nu + \delta) \omega^{2} - \delta\eta_{2}n^{2})^{-1},$$
  

$$X_{2}(\omega) = \tilde{K} + i\omega^{-1} (An^{4} - Bn^{2}\omega^{2} + \omega^{4}) (D\omega^{2} - Cn^{2})^{-1}$$

and do not become zero for Im  $\omega < 0$ . Let n > 0. Then on the edge  $\Gamma$  (Fig. 1,  $\omega_0 = n(\delta \eta_2)^{1/2}(\nu + \delta)^{-1/2}$ ), which encompasses the lower complex half-plane, we have that the following applies on account of (5) and (7):

$$\operatorname{Re} X_1(\omega) > 0.$$

As  $X_1(\omega)$  is holomorphic in the lower complex half-plane, that inequality is obeyed for all  $\omega$ , Im  $\omega < 0$ . If now we consider  $X_2(\omega)$ , on  $\Gamma$  (Fig. 1,  $\omega_0 = n(C/D)^{1/2}$ ) we have

$$\operatorname{Re} X_2(\omega) > 0 \tag{12}$$

subject to the additional condition

$$AD^2 - BDC + C^2 < 0. (13)$$

Because of the holomorphic behavior, (12) is obeyed for all  $\omega$ , Im  $\omega < 0$ .

We note that (13) is not too restrictive. For example, one can usually assume in practice that  $a_2 = 0$  (whence  $C_2 = 0$ ), while  $\delta$  and  $\nu$  are quantities of the same order, and  $C_1$  substantially exceeds  $C_3$  and  $C_4$ . Those conditions are sufficient for (13) to apply.

Then we can use (11), and (7) gives a result that extends the [6] conclusions:

$$V_{1} = \begin{cases} \eta_{2}^{1/2}, & \epsilon < 1, \\ \eta_{2}^{1/2} (1 + \delta_{x})^{1/2} (1 + x (\delta + \nu))^{-1/2}, & \epsilon = 1, \end{cases}$$
$$V_{2.3} = \begin{cases} 2^{1/2} (B \pm (B^{2} - 4A)^{1/2})^{1/2}, & \epsilon < 1, \\ 2^{-1/2} (1 + xD)^{-1/2} (B - xC \pm ((B - xC)^{2} - 4A (1 + xD))^{1/2})^{1/2}, & \epsilon = 1. \end{cases}$$

Here  $V_1$  is the limiting propagation speed for transverse perturbations, while  $V_2$  and  $V_3$  are the limiting propagation speeds for perturbations of the first and second types correspondingly (see [7] for terminology).



Fig. 1

When the (7) and (13) conditions apply, the signal speed is finite in relaxational infiltration. Situations can occur ( $\varepsilon = 1$ ) when internal relaxation in the porous medium-saturating fluid system influences the limiting perturbation propagation speed. This substantially supplements the [6] results.

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